

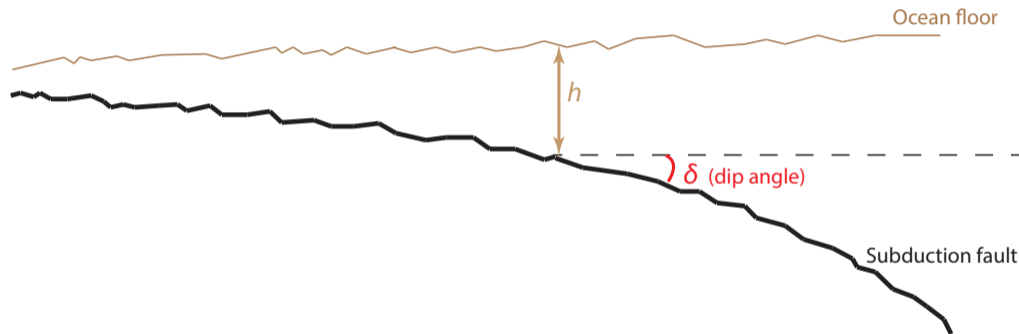
# Imaging shear strength along subduction faults

Quentin Bletery (University of Oregon)

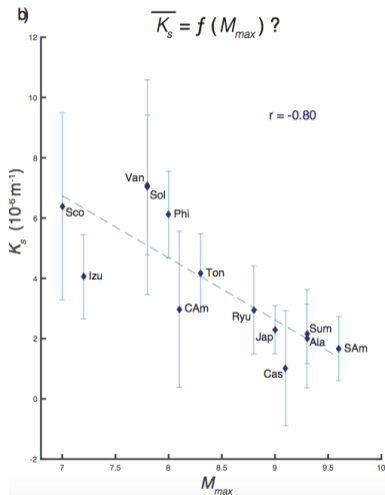
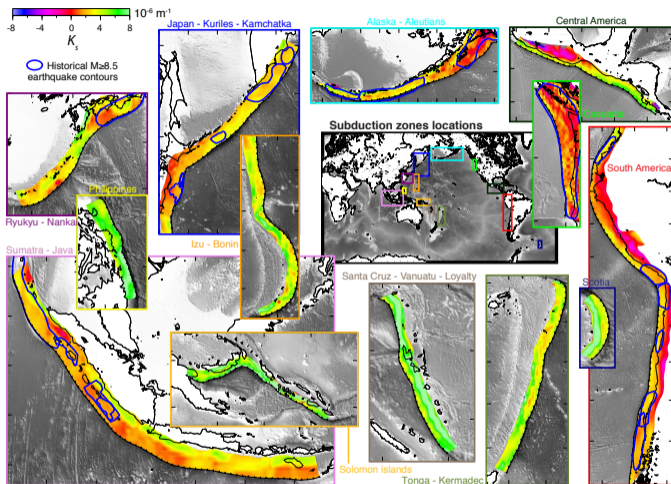
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Jeanne L. Hardebeck (USGS)

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# Subduction fault



# Mega-earthquakes rupture planar megathrusts ( $K_s$ : dip angle gradient)



Bletery et al., *Science*, 2016

## Control of geometry on the distribution of shear strength ?

$$\tau^c = \mu(\sigma_n - p)$$

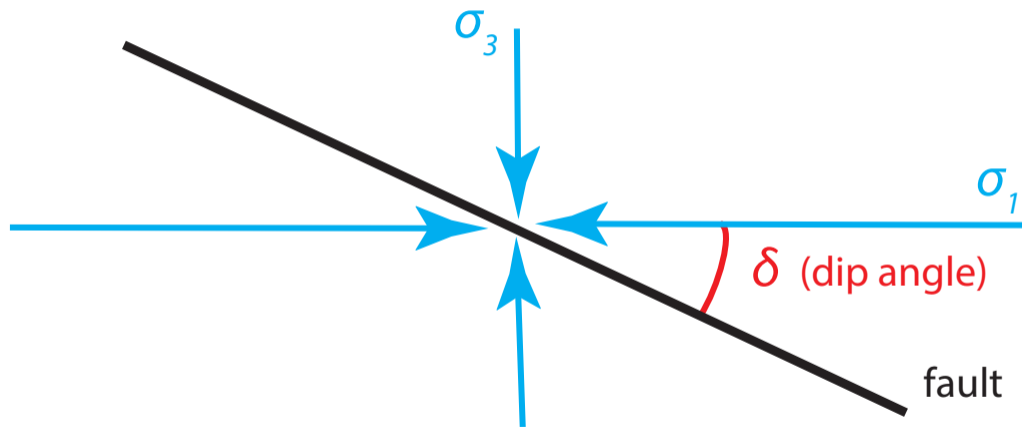
$\tau^c$  shear strength

$\mu$  coefficient of friction

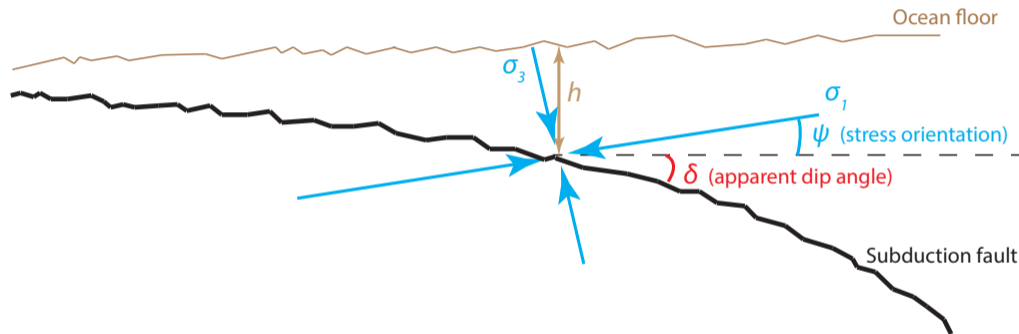
$\sigma_n$  normal stress

$p$  pore fluid pressure

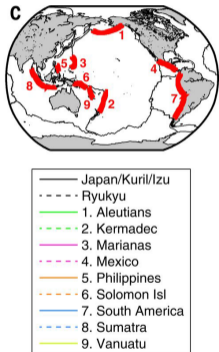
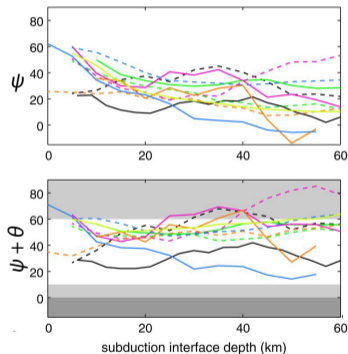
## Andersonian theory of faulting



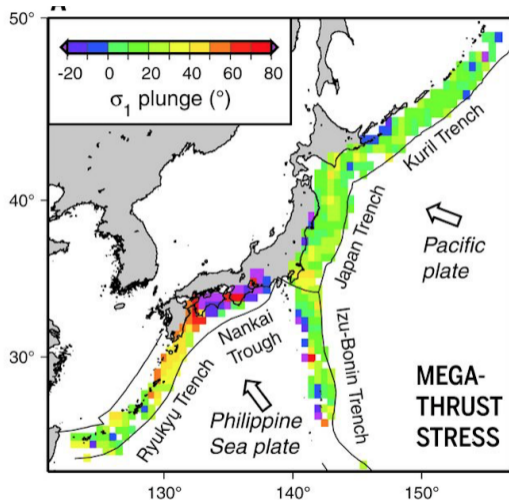
# Subduction model



# Stress orientation ( $\psi$ ) on subduction zones



Hardebeck, *Science*, 2015



Hardebeck, *Science*, 2015

## Analytic derivation of the shear strength $\tau^c$

$$\boldsymbol{\sigma} = \begin{pmatrix} \sigma_{zz} + \Delta\sigma & \frac{\Delta\sigma}{2} \tan 2\psi \\ \frac{\Delta\sigma}{2} \tan 2\psi & \sigma_{zz} \end{pmatrix}$$

$$\Rightarrow \begin{cases} \sigma_n = (\boldsymbol{\sigma} \cdot \mathbf{n}) \cdot \mathbf{n} = \sigma_{zz} + \frac{\Delta\sigma}{2} (1 - \cos 2\delta + \tan 2\psi \sin 2\delta) \\ \tau = (\boldsymbol{\sigma} \cdot \mathbf{n}) \cdot \mathbf{s} = -\frac{\Delta\sigma}{2} (\sin 2\delta + \tan 2\psi \cos 2\delta) \end{cases}$$

$$|\tau^c| = \mu(\sigma_n^c - p) \text{ (Mohr-Coulomb failure criterion)}$$

$$\tau^c = \frac{\mu(\sigma_{zz} - p) \sin(2\delta + 2\psi)}{\sin(2\delta + 2\psi) + \mu[\cos(2\delta + 2\psi) - \cos 2\psi]}$$

$\tau^c$  : shear strength

$\mu$  : coefficient of friction

$\sigma_{zz}$  : vertical stress

$p$  : pore fluid pressure

$\delta$  : apparent dip angle

$\psi$  : stress field orientation



## Numerical computation

$$\text{Assumptions : } \begin{cases} \sigma_{zz} = \rho gh & \text{Pressure of the upper plate} \\ \rho = \rho_w gh & \text{Hydrostatic pore pressure} \end{cases}$$

$$\tau^c = \frac{\mu(\rho - \rho_w)g h \sin(2\delta + 2\psi)}{\sin(2\delta + 2\psi) + \mu(\cos(2\delta + 2\psi) - \cos 2\psi)}$$

$$\delta = \arctan(\sin(\phi - \lambda) \tan \theta)$$

$\mu$  : coefficient of friction

$\rho$  : bulk density of the crust

$\rho_w$  : bulk density of water

$g$  : gravity acceleration

$\delta$  : apparent dip angle

$h$  : depth (slab1.0 + ETOPO2 models)

$\phi$  : strike angle (slab1.0)

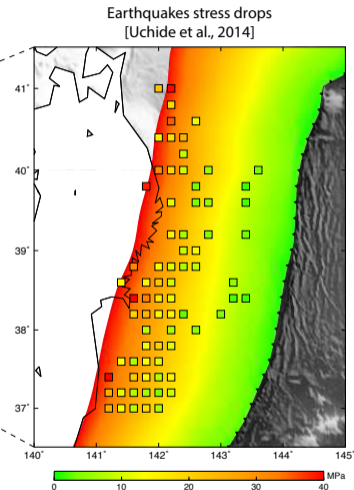
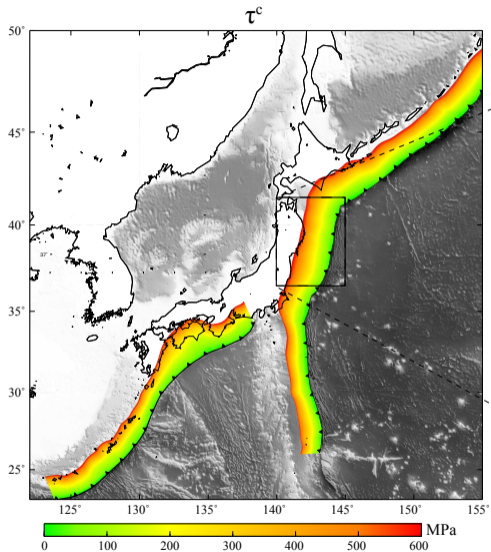
$\theta$  : dip angle (slab1.0)

$\lambda$  : convergence direction (NNR-MORVEL56)

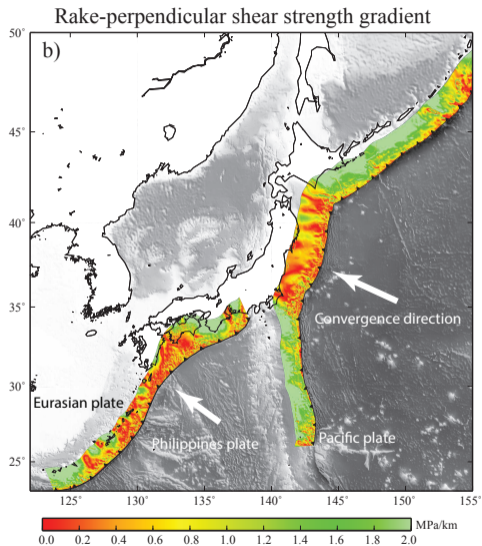
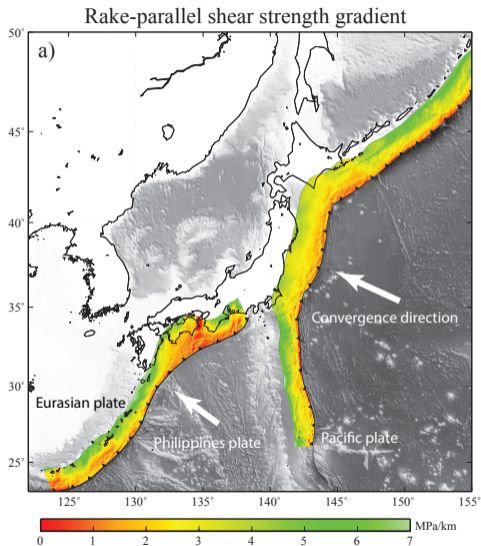
$\psi$  : stress field orientation (Hardebeck, *Science*, 2015)

$$g = 9.8\text{m/s}^2, \rho = 2700\text{kg/m}^3, \rho_w = 1000\text{kg/m}^3, \mu = 0.6$$

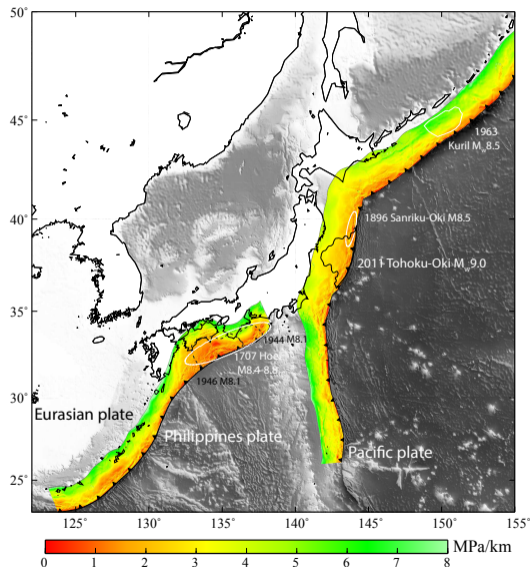
# Computed shear strength



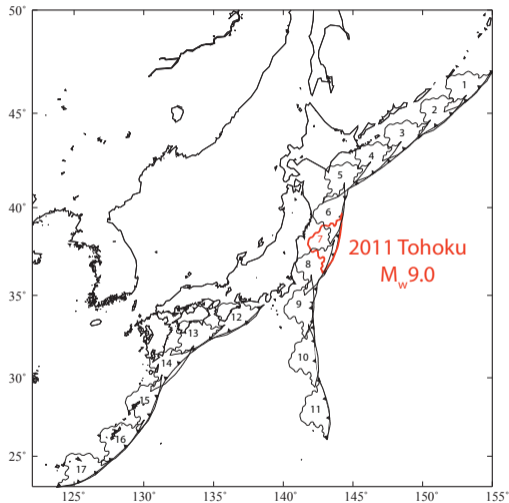
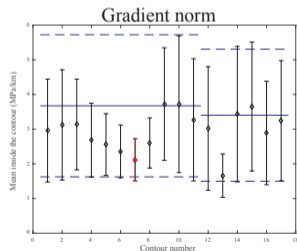
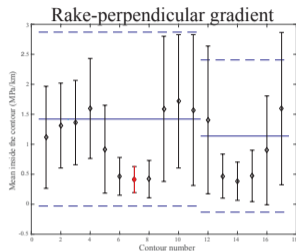
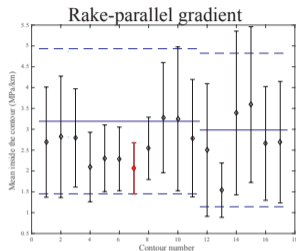
# Shear-strength gradient



# Norm of the shear-strength gradient



# Mega-earthquakes occur on areas of homogeneous $\tau^c$ (i.e. low $\tau^c$ gradient)



# Conclusions

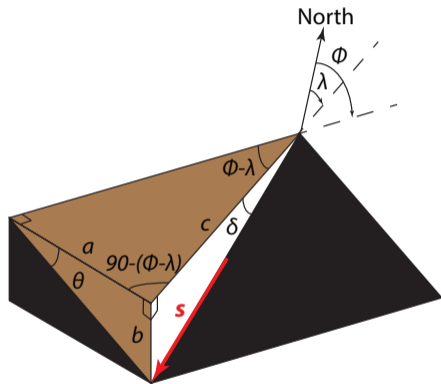
Variations of the shear strength ( $\tau^c$ ) may be estimated along subduction faults.

Mega-earthquakes seem to occur on areas of homogeneous shear strength.

Limitations : hydrostatic pore pressure  $p = \rho_w gh$  and constant  $\mu$  assumptions  
possible larger variations of  $\psi$  at small scale.

Perspectives : explore different pore pressure laws and variable coefficient of friction.  
Other subduction faults.

## Apparent dip angle



$$a = c \sin(\phi - \lambda)$$

$$b = a \tan \theta$$

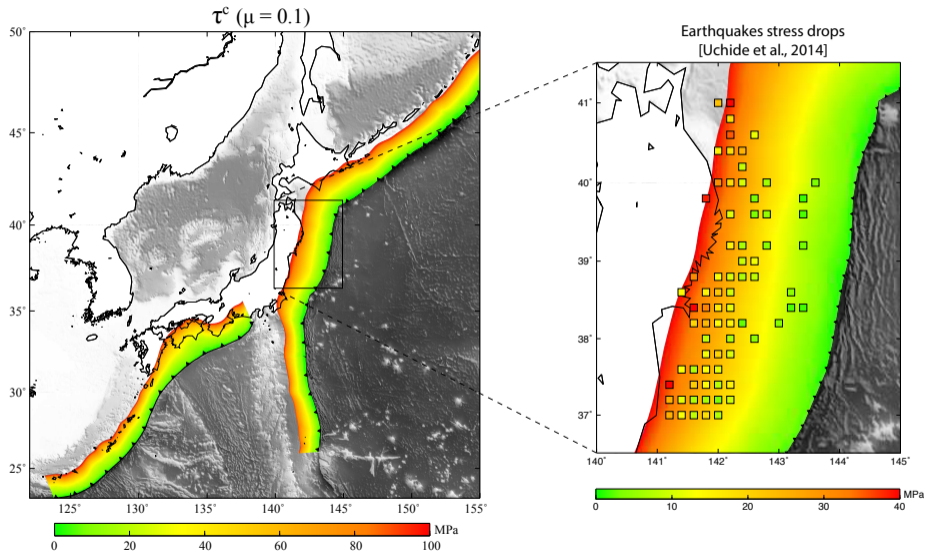
$$b = c \tan \delta$$

$$c \tan \delta = a \tan \theta$$

$$\tan \delta = \sin(\phi - \lambda) \tan \theta$$

$$\delta = \arctan[\sin(\phi - \lambda) \tan \theta]$$

# Computed shear strength assuming $\mu = 0.1$ instead of $\mu = 0.6$





# Mega-earthquakes occur on areas of homogeneous $\tau^c$ ( $\mu = 0.1$ )

